Gravitational Wave Astronomy With LISA

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- Image: Time-Delay interferometer.

⁴ -1 Hz	10 - Few KHz

Coalescing neutron

Stellar mass Blackhole mergers

Rotating Neutron/Compact Stars

Supernova

Ext. low Frequency Below -10 ⁻¹⁰ Hz	V Very low Frequency 10 ⁻⁹ -10 ⁻⁶ Hz	Low Frequency 10 ⁻⁴ -1 Hz	High Frequency 10 - Few KHz	
			Ground Based Detec	tors
			Such as LIGO, VIRC	GO etc

Coalescing SMB $< 10^7 M_s$ Galactic Binaries EMRI's

Ext. low Frequency	yVery low Frequency	Low Frequency	High Frequency
Below -10^{-10} Hz	10 ⁻⁹ -10 ⁻⁶ Hz	10 ⁻⁴ -1 Hz	10 - Few KHz
	ł		
	LISA	A	

Coalescing SMB up to $10^{11} M_s$

Stochastic GW background

Binary stars

Ext. low Frequency	Very low Frequency	Low Frequency	High Frequency
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	, t		7
Pulsar in Binary (Taylor Pulsar)			

Pulsar Timing

Doppler tracking of inter-planetary spacecrafts

Universe

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CMB

Sensitivity Curve

Reference LISA is sensitive to gravitational waves in the frequency range 10^{-4} Hz to 1 Hz.



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- $^{\rm I\!S\!S}$ White dwarfs have mass about $1-1.4\,M_\odot$ while their radius is only 1000 KM.
- In our Galaxy there 10^{11} stars and about 50% of them are binary system.

There millions of binary stars in the LISA band especially between 0.1 mHz to 3 mHz, and individual sources can not be resolved. These stars generate a stochastic noise the detector called white dwarf noise.



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- LISA observation can give distribution of them in our Galaxy and one can constrain the Galactic models based on LISA observations.



Super massive blackhole binaries

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It is seen that Galaxies collide,



Binary blackhole's are one of promising sources in the LISA band, can seen almost any where in the Universe.



Sensitivity curve for blackhole binaries:



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- Image They serve as test for Einstein theory in the strong field limit.
- Image Can be used to test the alternative theory of gravity.

Extreme mass ratio insprial(EMRI's)

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Galactic centers, such as our Galaxy hosts blackhole of mass $10^5 M_{\odot}$. Some of the stars orbiting around them can fall in to blackholes emitting gravitational waves:



 $^{\rm loc}$ Or one can have blackholes of mass $1-10~M_{\odot}$ falling into central blackhole

 $^{\hbox{\tiny INST}}$ We have small objects of mass 1 to $50~M_{\odot}$ falling in to blackholes of mass $10^6~M_{\odot}$ is called EMRI



Sensitivity curve for EMRI:



In order to observer astrophysically important sources such as these, one needs a space mission such as LISA.

Mission overview

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Six laser beams are exchanged between these three spacecraft to detect gravitational wave signal in the band $10^{-4} - 1$ Hz with peak sensitivity of $h \sim 10^{-23}$.



Each spacecraft hosts, two test masses and optical system to communicate with the distance spacecraft



LISA orbits



LISA orbits

- Each of the LISA spacecraft go around Sun, in elliptical orbits such that entire formation remain almost equilateral triangle.
- The plane of the LISA triangle makes an angle of 60° with the ecliptic plane.
- The center of this LISA constellation moves around the Sun in an earth-like orbit (R = 1AU), 20° behind the Earth.
- The triangular constellation revolves once around its center as it completes one orbit in the course of one year.

A choice of orbits



$$\tan \varepsilon = \frac{\alpha}{1 + \alpha/\sqrt{3}}, \qquad \alpha = \frac{l}{2R}$$

$$e = \left(1 + \frac{2}{\sqrt{3}}\alpha + \frac{4}{3}\alpha^2\right)^{1/2} - 1$$

$$\psi_1 = \Omega t$$

Orbits for other two spacecraft can obtained by rotating this by 180° about z - axis

Ψ

CW-Frame and Equations

Clohessy and Wiltshire or Hill's equations are linearised dynamical equations for test-particles in the neighborhood of reference point, in our case the LISA centroid. These equations are written in a frame which has its origin on the reference orbit and also rotates with angular velocity Ω . The equation for a free test particle are given by,

$$\begin{aligned} \ddot{x} - 2\Omega \dot{y} - 3\Omega^2 x &= 0, \\ \ddot{y} + 2\Omega \dot{x} &= 0, \\ \ddot{z} + \Omega^2 z &= 0. \end{aligned}$$

The solutions:

$$\begin{aligned} x(t) &= \frac{\dot{x}_0}{\Omega} \sin \Omega t - \left(3x_0 + \frac{2\dot{y}_0}{\Omega}\right) \cos \Omega t + 2\left(2x_0 + \frac{\dot{y}_0}{\Omega}\right) \\ y(t) &= \left(6x_0 + \frac{4\dot{y}_0}{\Omega}\right) \sin \Omega t + \frac{2\dot{x}_0}{\Omega} \cos \Omega t - 3\left(2\Omega x_0 + \dot{y}_0\right) t \\ &+ \left(y_0 - \frac{2\dot{x}_0}{\Omega}\right) \\ z(t) &= z_0 \cos \Omega t + \frac{\dot{z}_0}{\Omega} \sin \Omega t \end{aligned}$$

Ignoring runaway solutions and offset solution the condition for stable configuration is given by

$$z_0 = \mu \sqrt{3} x_0$$
 and $\frac{\dot{z}_0}{\Omega} = \frac{1}{2} \mu \sqrt{3} y_0$, $\mu = \pm 1$

The solutions are given by,

$$\begin{aligned} x(t) &= \frac{1}{2}\rho_0 \cos\left(\Omega t - \phi_0\right), \\ y(t) &= -\rho_0 \sin\left(\Omega t - \phi_0\right), \\ z(t) &= \mu \rho_0 \frac{\sqrt{3}}{2} \cos\left(\Omega t - \phi_0\right), \end{aligned}$$

where

$$\rho_0 = \sqrt{4x_0^2 + y_0^2}$$
 $\tan \phi_0 = \frac{y_0}{2x_0}$

The orbits given earlier when when approximated to first order in $\alpha = l/(2R)$ and transformed to CW frame we get:

$$x_{k} = eR\cos\left[\Omega t - (k-1)\frac{2\pi}{3}\right]$$
$$y_{k} = -2eR\sin\left[\Omega t - (k-1)\frac{2\pi}{3}\right]$$
$$z_{k} = \sqrt{3}eR\cos\left[\Omega t - (k-1)\frac{2\pi}{3}\right]$$

we identify $\rho_0 = 2eR$ and $\phi_0 = 2\pi(k-1)/3$

The general result is

In the CW frame there are just two planes which make angles of $\pm \pi/3$ with the (x-y) plane, in which test particles obeying CW equations perform rigid rotations about the origin with angular velocity $-\Omega$.

S. V. Dhurandhar et. al, "Fundamentals of the LISA Stable Flight Formation", *Class. Quantum Grav.* **22** 481(2005).

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- For locking Michelson like interferometer, distance between the end points must be integral multiple of $\frac{\lambda}{2}$, which is impossible in space.
- Because different lasers are used at eand points, laser noise play important role.

Image Section Section 4.1 ■ Lasers typically have a frequency fluctuation of the order:

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- In the case of ground based detectors, where both arms are exactly of same length (integral multiple of $\frac{\lambda}{2}$) and the laser noise cancels out.
- Time-Delay interferometry is one of novel technique suggested by Armstrong et. al (J.W. Armstrong, F.B Estabrook and M. Tinto, *Astrophys.* J. 527, 814(1999).) for constructing unequal arm interferometer in space
- In this method the individual beams are combined off-line after introducing suitable time delay corresponding to the light travel time across the arms to simulate the interferometer.



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Clearly,

$$\Phi_1(t) - \Phi_2(t) \neq 0$$





$$X_{1} = [\Phi_{1}(t - 2L_{2}) - \Phi_{1}(t)]$$
$$X_{2} = [\Phi_{2}(t - 2L_{1}) - \Phi_{2}(t)]$$



$$\begin{split} X_1 &= \left[\Phi_1 \left(t - 2L_2 \right) - \Phi_1 \left(t \right) \right] \\ X_2 &= \left[\Phi_2 \left(t - 2L_1 \right) - \Phi_2 \left(t \right) \right] \\ \text{Clearly,} \end{split}$$

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LISA is a more complex system. There are three arms and six beams.

Delay Operator

S. V. Dhurandhar et. al, "Algebraic approach to time-delay data analysis for LISA", *Phs Rev.* D65, 102002(2002), gr-qc/0112059.

Let a(t) be any arbitrary function of time and L_k be the length of the *k*th arm, then we define time delay operator for the arm *k* as,

$$D_k a(t) = a(t - L_k)$$

c = 1 and all the distances are measured in the unit of time.

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Some Properties of Delay Operator:

the delay corresponding to the length of $lL_1 + mL_2 + nL_3$ is, $D_1^l D_2^m D_3^n$ This is equivalent to successively applying the delay operator

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the delay corresponding to the length of $lL_1 + mL_2 + nL_3$ is, $D_1^l D_2^m D_3^n$ This is equivalent to successively applying the delay operator They commute: $D_1^k D_2^l = D_2^l D_1^k$







Ui's in +ve direction

 $U^1 = D_2 C_3 - C_1$

 $U^2 = D_3 C_1 - C_2$

 $U^3 = D_1 C_2 - C_3$

 $V^1 = C_1 - D_3 C_2$





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 $U^3 = D_1 C_2 - C_3$

Vi's in -ve direction

$$V^1 = C_1 - D_3 C_2$$

 $V^2 = C_2 - D_1 C_3$
 $V^3 = C_3 - D_2 C_1$







Known Noise cancellation solution


Laser noise Cancellation Data combination

A general data combination is given by the combination of U^i and V^i of the form

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 p_i and q_i are polynomial in D_i , This is clear from the properties of D_i

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A noise cancellation Data combination, we need to determine p_i and q_i such that,

$$\sum_{i=0}^{3} p_i V^i + q_i U^i = 0$$

We need to solve for (p_i, q_i) as functions of D_i .

The solution to this equation is well known in the algebra and forms a module called "*First Module of Syzygies*", over the polynomial ring D_i .

 \square Vector spaces are definedModules are defined overover field \mathscr{F} .ring \mathscr{R} .

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 Complex numbers ℂ form fields.
- Reference Basis can generate the complete vector space by taking the combination $\sum a_i v^i$ where $a_i \in \mathscr{F}$ and v^i 's are basis elements.

Modules are defined over ring \mathcal{R} .

The elements of ring in general do not have multiplicative inverse.

Set of polynomials are important example for rings. No inverse for Polynomial !

They are called generators! and any element of module can be written of the form $\sum p_i g^i$ where $p_i \in \mathscr{R}$ and g^i 's are the generators.

The Generators

The solutions are represented by generator with (p_i, q_i) ,

$$\begin{aligned} X^{(1)} &= \alpha &= (1, D_3, D_1 D_3, 1, D_1 D_2, D_2), \\ X^{(2)} &= \beta &= (D_1 D_2, 1, D_1, D_3, 1, D_2 D_3), \\ X^{(3)} &= \gamma &= (D_2, D_2 D_3, 1, D_1 D_3, D_1, 1), \\ X^{(4)} &= \zeta &= (D_1, D_2, D_3, D_1, D_2, D_3). \end{aligned}$$

With these generator any solution can be expressed as:

$$X(p_i,q_i) = \sum_{I=1}^4 \alpha_{(I)} X^{(I)}$$
 In general, $\alpha_{(I)}$ can be polynomials in D_i

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